



## RCA15-HR High Res - Rack Mounted Amplifier/Digitiser



*User Manual*  
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# Chapter 1 Introduction to RCA15-HR

The In Line Intelligent Strain Gauge Amplifier RCA15-HR is a compact Rack Mounted microprocessor based module specifically designed to control weighing applications where there is a requirement for high resolution. Its flexibility of design allows for the connection of most Strain Gauges, pressure or strain gauges over a wide range of sensitivity.

Basic modules offer the following facilities:-

A simple auto calibration of the highest and lowest weights required, an easy auto tare setting and peak hold facility. A password facility gives protection to setup parameters.

DC analogue outputs of 4-20mA and 0-10V are standard with full scaling over any desired range and the ability to invert these outputs if required.

Gain sensitivity is selectable via DIL switches between 0.5 and 200mV/V.

Several 'plug in' options are available. An optional relay output module provides for 2 set points and hysteresis can be applied to both set points together with In Flight compensation. Relays can be inverted and latched. All these facilities being set digitally in real engineering terms from the plug in programmer unit or from front panel display module. Both relay and analogue outputs have a high level of isolation.

Optional communications modules provide for 20mA noise immune current loop, RS232 or RS485 connections to a PC, PLC or mainframe. This allows for the input variable to be viewed and any setup parameters changed.

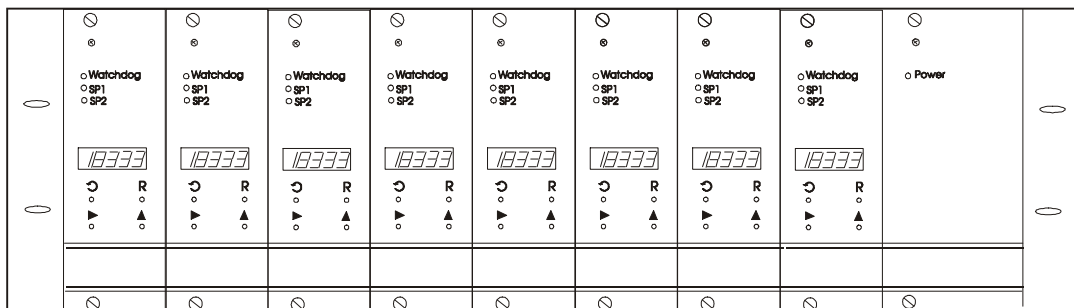
Multiple 20mA RCA15-HRs can be connected via an IF25 current loop to RS232 interface which, when included, allows for an expansion of up to 250 RCA15-HR modules.

The RS232 port is available for Time/Data or data only printers to be used, logging all desired activities.

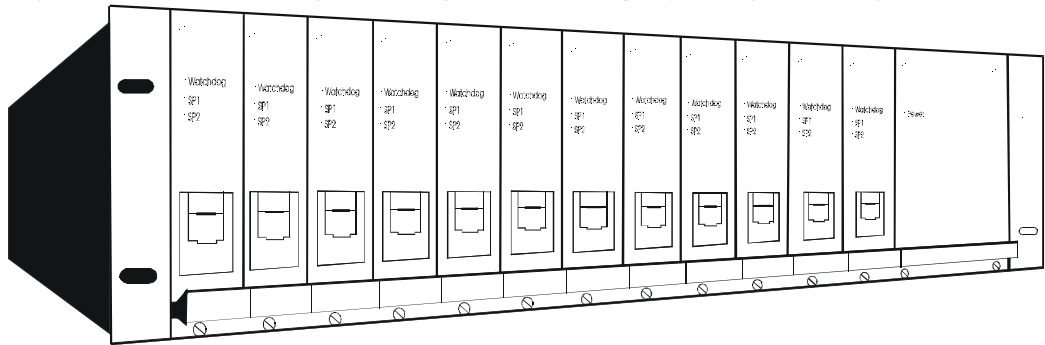
Baud speeds between 300 and 19200 are programmable.

The power supply module is available for 220/240V AC and 110/120V AC

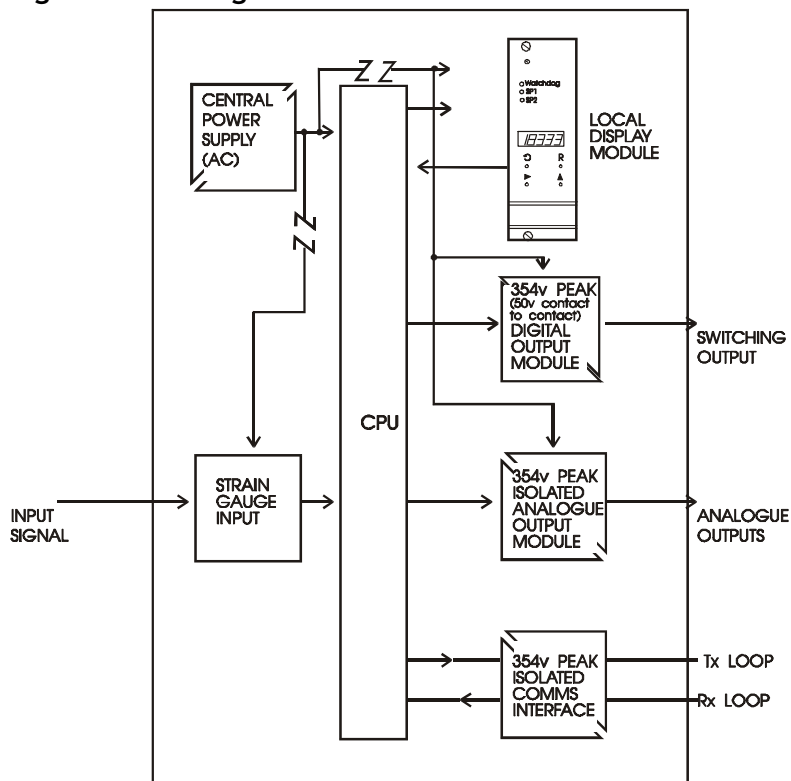
**Figure 1.1 RCA15-HR (RUA2-EX) Local Display/Programmer**



**Figure 1.2 RCA15-HR (RUA1-EX) Remote Display/Programming**



**Figure 1.3 A Single Channel RCA15-HR Unit**



## Chapter 2 Installing and Connecting the RCA15-HR

In order to maintain compliance with the EMC Directive 2004/108/EC the following installation recommendations should be followed.

**Inputs:** Use individually screened twisted multipair cable. (e.g. FE 585 - 646)  
The pairs should be :  
pins 1 & 6  
pins 2 & 5  
pins 3 & 4  
Terminate all screens at SCR. The screens should not be connected at the transducer end of the cables.

**Comm's Port:** Use individually screened twisted multipair cable. (e.g. FE 118-2117)  
the pairs should be:  
-Tx & +Tx  
-Rx & +Rx  
Terminate screens at SCR.  
The screens should not be connected at the host port.

**Analogue Output:** Use screened twisted pair cable. (e.g. RS 626-4761)  
Terminate screen at SCR.  
The screen should not be connected at the host port.

SCR should be connected to a good Earth. The Earth connection should have a cross-sectional area sufficient enough to ensure a low impedance, in order to attenuate RF interference.

### Cable Information (For Reference only)

Country	Supplier	Part No	Description
UK	Farnell	118-2117	Individually shielded twisted multipair cable (7/0.25mm)- 2 pair Tinned copper drain. Individually shielded in polyester tape. Diameter: 4.1mm Capacitance/m: core to core 115 pF & core to shield 203 pF
UK	Farnell	585-646	Individually shielded twisted multipair cable (7/0.25mm)- 3 pair Tinned copper drain. Individually shielded in polyester tape. Diameter: 8.1mm Capacitance/m: core to core 98 pF & core to shield 180 pF
UK	RS	626-4761	Braided shielded twisted multipair cable (7/0.2mm)- 1 pair Miniature- twin -round Diameter: 5.2 mm Capacitance/m: core to core 230 pF & core to shield 215 pF

## Environmental Requirements

RCA15-HR units can operate in any industrial environment provided the following limits are not exceeded at the point of installation:

Operating Temperature: -10 °C to 50 °C  
 Humidity: 95 % non condensing  
 Storage Temperature -20 °C to +70 °C

Units can operate from the following:-

220/240V AC, 50/60Hz                      110/240 Selected by a switch on the rear or the power supply module  
 110V AC, 50/60Hz

or

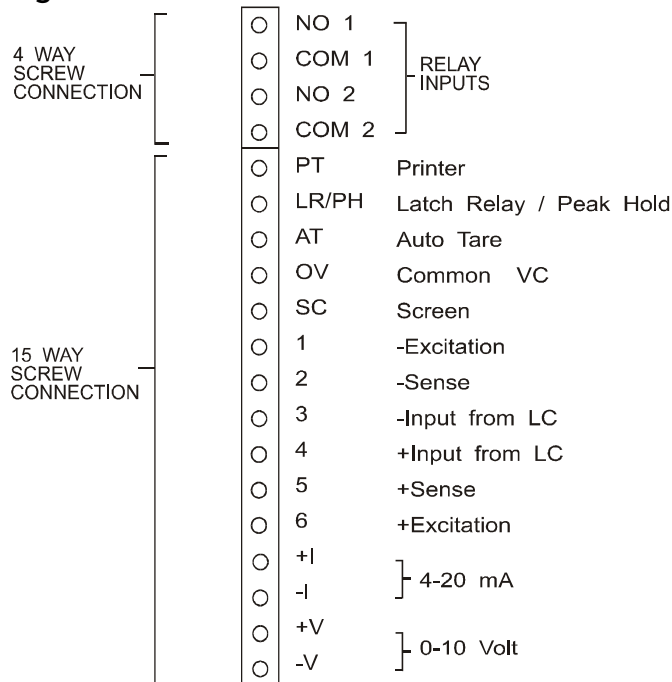
9-30V DC, 10W                                      A 5 Amp protection fuse is fitted within power input socket

## Terminal Connections

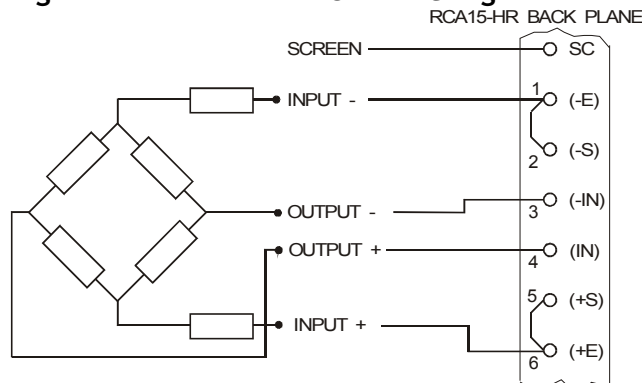
Connection between the RCA15-HR modules and input/output signals, are made via screw connections to the rear of the rack.

(See Figure 2.1)

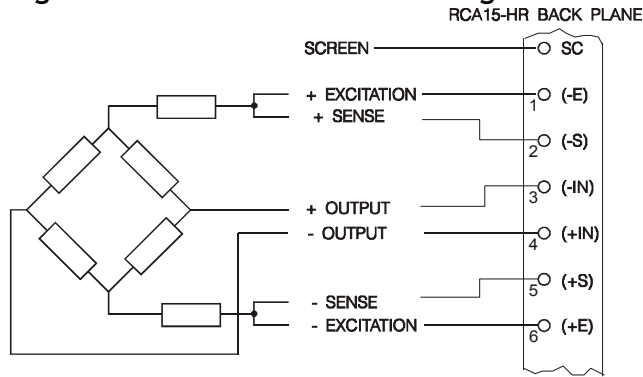
**Figure 2.1 RCA15-HR Back Plane Connection Terminals**



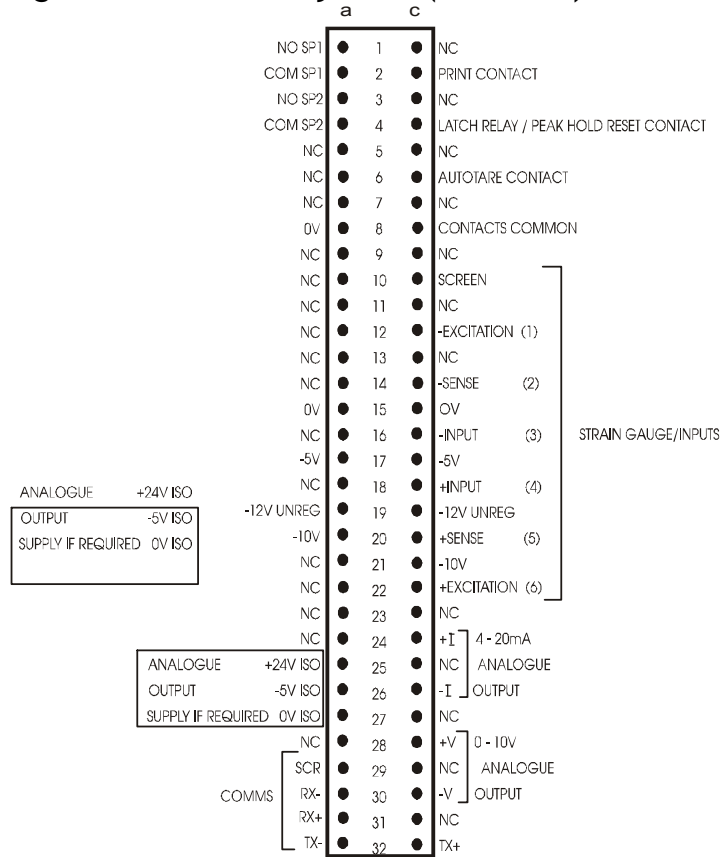
**Figure 2.2 The 4 Wire Strain Gauge**



**Figure 2.3 The 6 Wire Strain Gauge**



**Figure 2.4 The 32 Way A & C (DIN41612) Connections**





**Table 2.1**

	Supply	Connection to DIN 41612	Min V	Max V	Max AC V	Current	Comments
Processor Supplies	0V	15a, 15c	-	-	-	-	Common for Processor Supplies
	-5V	17a, 17c	-4.80	-5.2	1mA	110mA	Power Supply
	-14V Unreg	19a, 19c	-11	-18V	150mV	2mA	Used to detect Power Fail
	-9V8	20a, 20c	-9.1	-10.2	1mV	200mA	Provides excitation for Strain Gauges & Relays

**Table 2.2**

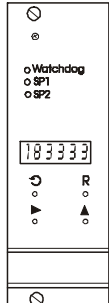
	Supply	Connection to DIN 41612	Min V	Max V	Max AC	Current	Comments
Analogue Output Isolated Supply	+24V ISO	25a	+20	+32	240mV	32mV	Only required if AN-OP is used
	-5V ISO	26a	-4.75	-5.25	1mV	5mV	
	0V ISO	27a	-	-	-	-	

## Chapter 3 The RCA15-HR Controls and Configurable Parameters

RUA2-EX All user controls, displays and indicators are mounted on the front panel which provides a 4.5 digit, LCD display and four programming keys accessed through 2.2mm holes in the front panel.

A flashing ----- symbol in the top left hand corner of the display indicates programming mode.

**Figure 3.1 Programmer Unit Panel Layout RCA15-HR (RUA2-EX)**



### Control Panel Guide



Used to scroll through and change the set up data by displaying mnemonics for each configurable parameter, followed by the appropriate data.


When in programming mode it should be noted that the first digit in the display may not be visible, but the program indicator --- will be flashing to indicate that the instrument is in programming mode, even though no digits can be seen to be flashing.



Selects the display digit required. Selection value is indicated by a flashing digit and flashing program indicator.



Increments each selected display digit 0-9.

Pressing the  key under programming conditions will display the leading digit as either 1, -1, or a blank display for zero.



Resets the display to the input variable and enters new data in the LCA15 memory. Returns the display to the current value after Hold.

If during the programming sequence, selection is not completed, the display will revert to the input variable after 2 minutes.


The display and controls on the front panel mounted version (RL2) operate in a similar way to the remote display/programmer described above, with program buttons being accessed through 2.2mm holes in the panel.

### The Configurable Parameters

A series of parameters or programmable functions are provided in the RCA15-HR to allow the user good flexibility for monitor and control applications.

These parameters are included as constants in the RCA15-HR database and are accessed and checked via the programmer keypad or the communications port.

Data which is entered by the user is retained by EEPROM for up to 10 years without back up power.

New data, when entered, overwrites previous entries when the  key is pressed unless the EEPROM has been disabled via the communications port.

## Section 1 - User/Engineer - Configurable Parameters

### Password Protection

A 4 digit password number must be entered. The number is accessed when 'PASS' is displayed. At this point, it is necessary to enter either the factory set number (contact supplier).

Code	Function	Value
trAn	Not applicable, will default to	000000
PASS	Security Password	(contact supplier)
SEtPt1	Setpoint 1	±999999
In-Ft1	In-Flight 1	±999999
SEtPt2	Setpoint 2	±999999
In-Ft2	In-flight2	±999999
HYS	Hysteresis for setpoint 1 & 2	±999999
LAtCH	Latch for setpoint 1 & 2	000000 to 000003
ACtion	Output action	
Bit value 1	invert SETP1	
Bit value 2	invert SETP2	
Bit value 4	invert an-op	
Bit value 8	Disp = Gross	
Bit value 16	Setpoint = Gross	
Bit value 32	An-op = Gross	
Bit value 64	Printer = Gross	
Bit value 128	Disp = Peak	
Bit value 256	Setpoint = Peak	
Bit value 512	An-op = Peak	
Bit value 1024	Printer = Peak	

Peak can be either Gross or Net value by selecting bit value 8 or not.

*Example, peakhold of gross value on display & An-op = 8 + 128 + 512 Peakhold can be reset from 'LR' contact.*

OP LO	Output Low for An-op scaling	±999999
OP Hi	Output high for AN-op scaling Auto Tare value	±999999
A-tArE	Not applicable, will default to	±999999
SCStdY	Display resolution of last digit. This function is performed on the display data only and does not affect the comms or printer.	000000
rESOL		000000 to 000250
CP	Comms Protocol. Selects printer or 'FAST MANTRABUS' format. 'CP' = 0 - 127 sets Printer. 'CP' = 128 sets 'FAST MANTRABUS' communications protocol. See comms and printer section of manual for further details. 'CP' = 130 sets Modbus Protocol	000000 to 000130
SdSt/	Sets Serial Device Station Number if 'CP' = 128. This sets a unique address code for each RCA15-HR See comms section.	000000 to 000254
LABEL	Sets label for the Printer if 'CP' = 0 - 127. See the printer section	000000 to 000254
Log no	Log Number A range of numbers 0 to 19,999 is available. Any sequential number logging activity can be preset as desired, between these numbers. The number will reset to zero after 19,999. The log number is not saved on power fail and resets to zero on power up.	

## ***Section 2 - Calibrators - Configurable Parameters***

### **Password Protection**

A 4 digit password number must be entered. The number is accessed when 'PASS' is displayed. At this point, it is necessary to enter Password number (contact supplier).

Code	Function	Value
trAn	Not applicable, will default to	000000
PASS	Security Password	(contact supplier)
CALL	Calibration Low value for mV/V display. Must be less than CALH. See calibration section.	±999999
CALH	Calibration High value for mV/V display. When CALH is set to zero the RCA15-HR will display the raw A/D value of between 0 & 524287. See calibration section.	±999999
AdCALL	A/D Calibration low value for CALL. Must be lower input mV than CALH A/D value. See calibration section.	0-524287
AdCALH	A/D Calibration high value for CALH. See calibration section.	0-524287
InPUTa	Cal point 1.mV/V value for Lin conversion. See calibration section.	±999999
dISP A	Cal point 1.Display value for Lin conversion. See calibration section.	±999999
InPUTb	Cal point 2.mV/V value for Lin conversion. See calibration section.	±999999
dISP b	Cal point 2.Display value for Lin conversion. See calibration section.	±999999
InPUTc	Cal point 3.mV/V value for Lin conversion. See calibration section.	±999999
dISP C	Cal point 3.Display value for Lin conversion. See calibration section.	±999999
InPUTd	Cal point 4.mV/V value for Lin conversion. See calibration section.	±999999
dISP d	Cal point 4 Display value for Lin conversion. See calibration section.	±999999
dP	Decimal Point position for currently selected Transducer. The following shows the position of the decimal point to	000000 to 000005
	Code      Position	
	000000    999999	
	000001    9.99999	
	000002    99.9999	
	000003    999.999	
	000004    9999.99	
	000005    99999.9	
A-tArE	Auto Tare value	±999999
SCStdY	Not applicable, will default to	000000
dISP AU	Number of A/D readings taken before the display is updated. This in conjunction with 'FILTER' sets the display update rate	000001 to 000255
rESOL	Display resolution of last digit. This function is performed on the display data only and does not affect the comms or printer.	000000 to 000250
t-SEnS	Keypad setting of Gain. Used in conjunction with link LK1 on input module to provide the following gains in mV/V, 1.25, 2.5, 5, 7.5, 15 & 30. Note: 't-SEnS' must be set before Auto calibration takes place. See calibration section for more detail	000000 to 000002

FILtEr	Sets the A/D sample frequency and notch Filter. This is factory set to 1953 and should not be adjusted. See calibration section.	000019 to 002000
CP	Comms Protocol. Selects printer or 'FAST' format. 'CP' = 0 - 127 sets Printer. 'CP' = 128 sets 'FAST MANTRABUS' communications protocol. See comms and printer section of manual for further details. 'CP' = 130 sets Modbus Protocol	000000 to 000130
SdSt/	Sets Serial Device Station Number. This sets a unique address code for each RCA15-HR See comms section.	000000 to 000254
LAbEL	Sets label for the Printer if 'CP' = 0 - 127. See the printer section	000000 to 000254
Log no	Log Number A range of numbers 0 to 19,999 is available. Any sequential number logging activity can be preset as desired, between these numbers. The number will reset to zero after 19,999. The log number is not saved on power fail and resets to zero on power up.	

# Chapter 4 Strain Gauge Input to the RCA15-HR

## The Strain Gauge Input

The RCA15-HR offers a direct connection to most low level (foil) strain gauge sensors.

A 10 volt excitation is provided and it is monitored to compensate for any variation due to supply drift, load regulation or voltage drop in the cable between the sensor and the RCA15-HR.

The maximum supply current is 160mA which allows for the connection of 4 x 350 Ohm Strain Gauges.

The RCA15-HR's A/D provides 19 bits of resolution (1 in 500,000). The Gain of which can be selected by means of a gain link on the input board (LK1) & by the 't-SEnS' mnemonic. Below is a table showing the relationship between the Gain link & the 't-SEnS' mnemonic.

MV/V INPUT GAIN	LINK LK1	't-SEnS' SETTING
1.25mV/V	Fitted	2
2.5mV/V	Fitted	1
5mV/V	Fitted	0
7.5mV/V	Not Fitted	2
15mV/V	Not Fitted	1
30mV/V	Not Fitted	0

Default setting is gain link fitted with 't-SEnS' set to 1 i.e. 2.5mV/V

The A/D Sample frequency & Notch filter can be set using the 'FILtEr' setting. The A/D can sample at frequencies of 10Hz to 1KHz. The value set in 'FILtEr' is calculated as

$$\text{FILTER} = 19531 / \text{Required sample in Hz}$$

The resolution of the A/D is changed with the value set in 'FILtEr' as outlined in the table below.

Filter	Data o/p rate in Hz & first notch of filter	Resolution in bits	-3db Frequency in Hz
1953	10	19	2.62
781	25	17.5	6.55
390	50	17	13.10
325	60	16.5	15.72
195	100	16	26.20
78	250	12.5	65.50
39	500	10.5	131.00
19	1000	8	262.00

Min value of 'FILtEr' is 19. (Limit of A/D)

**This value is Factory Set to 1953 and should not be changed without consulting the factory.**

Display update frequency is set by the A/D update rate set in 'FILtEr' & 'dISPAU' which sets the number of A/D readings to be averaged before display and communications ports are updated.

### Calibration

Switch on the RCA15-HR and allow it to stabilise for 30 minutes to obtain the best performance

*It is important that the gain, set by 't-sens' & LK1, is correct for the strain gauge sensitivity before proceeding with the calibration*

Apply a test weight of about 5% of required operating range to the Strain Gauges.

Enter the menu using the password from Chapter 3 Section 2, scroll to 'CALL'. Enter programming mode and set 'CALL' value to that of the applied weight. For calibration to be successful program mode must be entered even if 'CALL' has the required value already set. Use the scroll key to move onto 'CALH'.

Apply a test weight of about 80% of required operating range to the Strain Gauges.

Enter programming mode and set 'CALH' value for the applied weight. Again program mode must be entered even if 'CALH' has the required value already set.

*For calibration to be successful the 'CALL' calibration weight must be less than the 'CALH' weight.*

Press the **R** key, the calibration constants will now be stored into EEROM. the display will revert to the live input value which should be that of 'CALH'.

The values for 'ADCALL' and 'ADCALH' are automatically inserted once the auto calibration routine is completed. These values should **NOT** be altered. It is advisable however, to record the values for 'CALL', 'CALH', 'ADCALL' & 'ADCALH' as should these values be lost through operator error they can be re-entered from the keypad without the need of repeating the above procedure.

#### 4 Point Linearisation

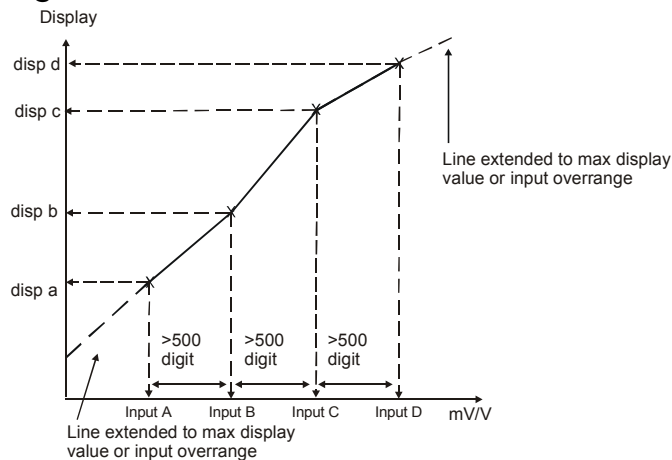
Any non linearity of the system may be reduced by using a 4 point linearisation routine. The 4 points being entered under mnemonics 'InPUt A' to 'dISP d'.

System non-linearity can be determined by plotting a graph of weights applied against display value. 3 straight lines can be applied to this curve, the end of each line providing one of the 4 linearisation points. These are entered as display value for non-linearised 'InPUt' against required 'dISP' value.

Notes on 4 point linearisation (See Figure 4-1)

- 1) All 4 points must be entered
- 2) A minimum value of 500 digits between each value must be observed.
- 3) The line is extended above point 'd' in a straight line set by point 'C' & 'd'
- 4) The line is extended below point 'A' in a straight line set by point 'A' & 'b'
- 5) If all 4 points are set to zero then no linearisation is applied.

**Figure 4.1 Internal Linearisation Protocol**





## Chapter 5 Analogue Outputs

Two analogue outputs are available offering a DC current range and a DC voltage range. They are fully scalable, optically isolated and generated from the displayed input value. The 4 to 20 mA output is pre calibrated to an accuracy of within 0.15% of the range. The 0-10V output is accurate to within 2% of the 4 to 20mA output.

OUTPUT	RANGE
DC voltage	0V to 10V
DC current	4 to 20mA

Notes:

1. Maximum current load on voltage modules is 2mA
2. Maximum drive voltage available in current modules is 20V.
3. Accuracy 4-20mA  $\pm 0.15\%$  of range, typical. Resolution as for display up to 13 bits/4.5 digits. Settling time 0.25 secs to 1% of step change.
4. Isolation  $\pm 130V$  RMS or DC max to analogue input or any other port. Common to other analogue outputs in the same rack.

### Output Scaling

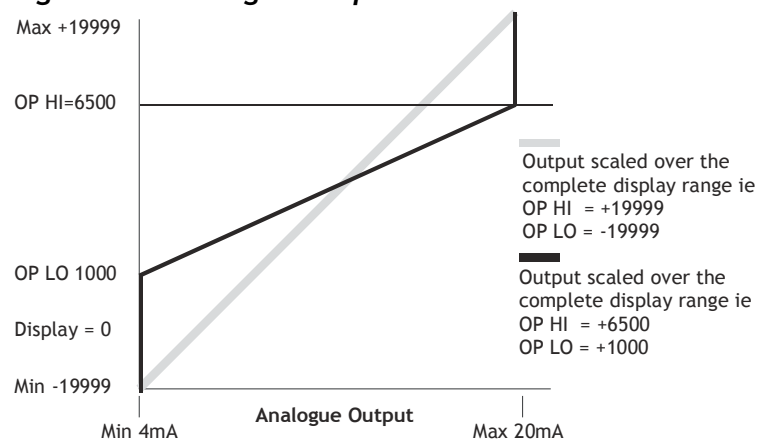
Output scaling factors are set by the user and determine the display range over which the analogue module operates. (OP LO) Output Low - This sets the displayed value at the modules minimum output. (OP HI) Output High - This sets the displayed value at maximum output. If the display is outside the range defined by OP LO and OP HI, the analogue output will remain constant at its minimum or maximum output value.

Inversion of the analogue output can be set by the output action mnemonic OA (See Relay Output Module Chapter 6).

Example: Assume a 4-20mA output module is required to provide an output of 4mA for 1000Kg and 20mA for 6500Kg. Set OP LO to 1000 and OP HI to 6500

It will be necessary to determine OP LO and OP HI by graphical or mathematical means if the known display values do not coincide with the minimum and/or maximum analogue output.

**Figure 5.1 Analogue Output**



### Method of Calculating OP LO and OP HI from any known output values

$$\text{OP LO} = \frac{\text{Low Display} - (\text{Display span}) (\text{Low output} - \text{Min output})}{(\text{High output} - \text{Low output})}$$

$$\text{OP HI} = \frac{\text{High Display} + (\text{Display Span}) (\text{Max output} - \text{High output})}{(\text{High output} - \text{Low output})}$$

Low output = Known low output

High output = Known high output

Min output = Lowest measurable value of output module

Max output = Highest measurable value of output module

Display span = Highest required display value minus lowest required display value.

Example:

Using a 4.20mA output module where it is required to produce 6mA at a display value of 400 and 18mA at a display value of 1100.

$$\text{OP LO} = 400 - \frac{(700) (6 - 4)}{(18 - 6)} = 400 - \frac{1400}{12}$$

$$\text{OP LO} = 400 - 116.66$$

$$\text{OP LO} = 283.34$$

$$\text{OP HI} = 1100 + \frac{(700) (20 - 18)}{(18 - 6)} = 1100 + \frac{(700 \times 2)}{12}$$

$$\text{OP HI} = 1100 + 116.66$$

$$\text{OP HI} = 1216.66$$

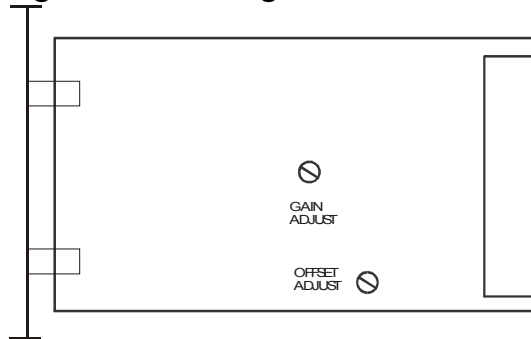
Note 1: OP HI must be greater than OP LO

Note 2: If OP LO or OP HI are greater than  $\pm 19999$  then divide both OP LO and OP HI by 10, this will give less resolution. Decimal point can be placed anywhere to suit reading.

### Calibration

Re calibration can be made by adjusting the gain and offset potentiometers, or by adjusting the values of OP LO and OP HI. An offset can be achieved by increasing the values of both OP LO and OP HI, and the gain by increasing the range between OP LO and OP HI.

**Figure 5.2 Showing the Potentiometers for Gain and Offset Adjustment**



## Chapter 6 Relay Output Module

### General Description

The Relay output module provides output control signals which can be used for switching functions such as ON/OFF control and alarm indications. The relays are activated by the values programmed for the Set Points. The output configuration will be for open or closed relay contacts and latching.

Output	Function
2 Relays	SPCO on SETPT1 and SETPT2

The connections for which are shown on Chapter 2.

### Module Functions

The RCA15-HR can be programmed so that the relay output module reacts to all or any of the following functions:

- Set points
- In Flight compensation
- Hysteresis
- Relay inversion
- Latching

### Set Points (SP)

Set points are used to produce output signals at any required value so that the operation of the monitored process can be maintained to preset levels. Any excursion beyond set points will activate the relay or relays, to provide alarm or initiate control as required.

Two set points (SETPT1) and (SETPT2) can be programmed to suit different applications. The actions of either or both set points can inverted if required. For normal operation the set point output is active until the input reaches the set point level. In this condition when the input value is less than the set point, the SETPT indicator is on and the output relay is energized producing a closed circuit on a normally open contact. When the set point value is reached, the SETPT indicator is off and the relay is de-energized producing an open circuit output. For an inverted operation the reverse conditions apply.

Normal and inverted action is determined by the direction of the input value as it changes. For example: In alarm applications.

A High-High operation allows for a rising input value to operate on two set points to define an acceptable quantity, weight or band of operation.

A Low-Low operation operates on a falling value.

A High-Low operation will operate on a rising or falling value, setting a 'band' by one set point operating normally and the other being an inverted action.

### In Flight Compensation

The setting of an In Flight value causes the set points to automatically adjust to control the flow of the material being weighed.

For example, if SETPT1 is used to control a flow, a certain amount will be 'In Flight' between the supply point and receiving point causing a positive error when the required weight is reached. The In Flight compensation value is adjusted by the user to 'reduce' SETPT1 to prematurely stop the flow, allowing the In Flight amount to make up the required total set by SETPT1. A similar situation exists for SETPT2.

### Hysteresis (HYS)

Once a Hysteresis value has been set, it will be applied to both set points entered. It is effective for both normal and inverted action.

When Hysteresis is applied to set points with normal output action, the input is allowed to rise to the set point

value and the output is then turned off. The output is held off until the input value has dropped to the set point minus the Hysteresis value.

For inverted action the input drops to the set point and the output goes off and comes on again when the input rises to the set point plus the Hysteresis value.

### **Output Action (Action)**

The Output Action facility allows the user to determine whether set points produce normal or inverted output operation. If an analogue output module is also fitted, the Output Action function determines whether the module's output is inverted or not. The Output Action (ACTION) is entered by a code to suit the requirements of the user. Sixty four Output Action options are available.

The value of the ACTION to be entered is the algebraic sum of the following components:-

Bit value 1	invert SETPT1
Bit value 2	invert SETPT2
Bit value 4	invert an-op
Bit value 8	Disp = gross
Bit value 16	Setpoint = gross
Bit value 32	An-op = gross
Bit value 64	Printer = gross
Bit value 128	Disp = Peak
Bit value 256	Setpoint = Peak
Bit value 512	An-op = Peak
Bit value 1024	Printer = Peak

Peak can be either Gross or Net value by selecting bit value 8 or not.

*Example, peakhold of gross value on display & An-op = 8 + 128 + 512 Peakhold can be reset from 'LR' contact.*

### **Latching Outputs (LAtCH)**

The latching facility allows the relay module output to be held until reset either by keypad, external remote or via the communications port. Latching is applied to the off status of the relay SETPT1 or SETPT2.

SETPT1	SETPT2	Code
Unlatched	Unlatched	0
Latched	Unlatched	1
Unlatched	Latched	2
Latched	Latched	3

# Chapter 7 The Communications Port

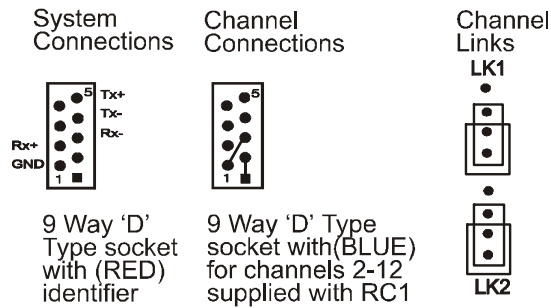
## Introduction

The RCA15-HR communications port provides for a 2 way data link. An intelligent host e.g. Personal Computer, Main Frame or PLC is able to acquire the RCA15-HR's displayed value and read or modify the user configurable parameters, using any of the following:-

### RC1 Communications Connections - Current 1 Loop

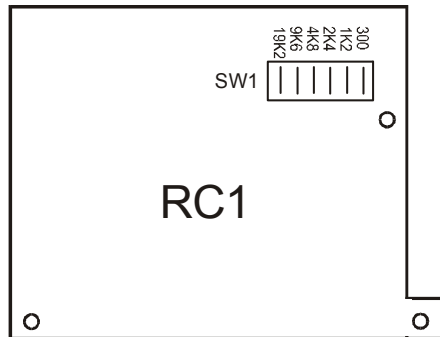
RC1 used in connection with an IF25 to provide a high noise immunity 20mA current loop. RC1 modules are supplied with a blue 9 way bus terminating header. One of these headers must be connected to each channel fitted with an RC1 module. Channel 1 is terminated by links LK1 & LK2 on backplane.

**Figure 7.1 RC1 Communication Connections**



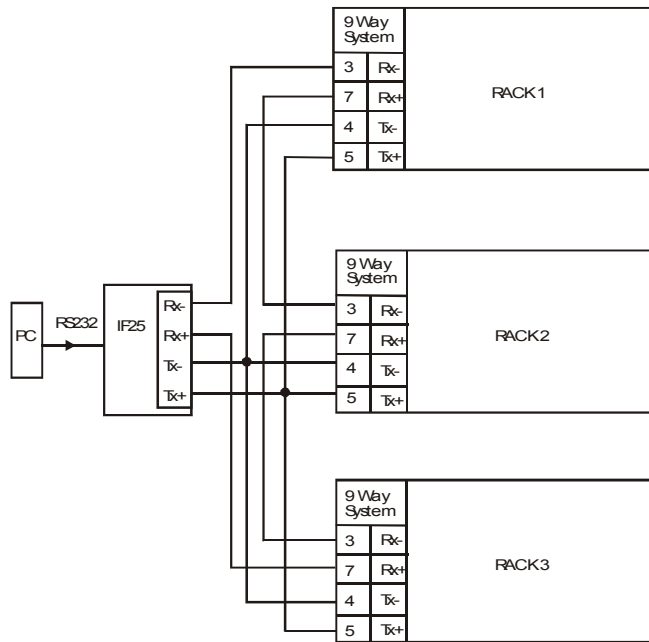
**Figure 7.2 RC1 Baud Rate Selection**

Baud rate is selected by a link header (SW1)



### Figure 7.3 Connecting Multiple RCA15-HRs

#### IF25 To Multi Rack System



Notes:

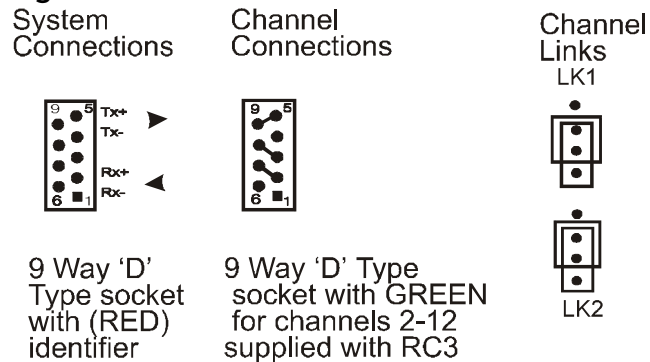
1. Maximum loop voltage is 50V dc.
2. Loop is isolated from host and RCA15-HRs. Loop should be earthed via Rx - on IF25/254
3. IF25 used for up to 25 RCA15-HRs.
4. At 19,200 Baud, max. cable length is 100m meters, using cable type BICC H8085.

### RC3 (RS232/485) Communication Connections

Providing isolated multi-drop RS485 for up to 25 RCA15-HR Channels.

For each RC3 module a GREEN 9 way bus terminating header is supplied. One of these must be connected to each channel fitted with an RC3 module. Channel 1 is terminated by links LK1 & LK2 on back plane.

#### Figure 7.4 RC3 RS232/485 Communications Connections

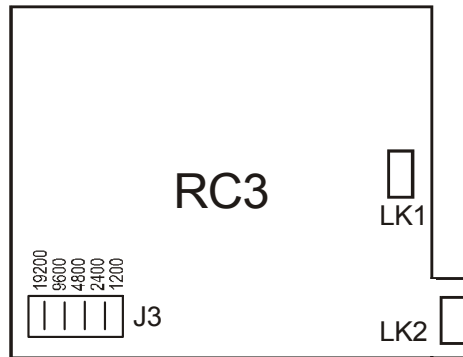


Note: The last device may be terminated by 120R resistor by fitting LK2 on RC3 module. LK1 on RC3 must not be fitted for multi-drop applications.

#### Figure 7.5 RC3 Baud Rate Selection

Baud Rate is selected by a link header (J3)

Do not change baud setting with power on



**NOTE:**

When using an RS232 to RS485 converter which has a non-biased receiver, the following actions are recommended:-  
To bias the device:

1. Terminate the receiver with 140R in place of the usual 120R
2. Fit a 1.5K from the receive negative to the receiver +5V supply, or a 3K3 to the +12V supply.
3. Fit a 1.5K from the receive positive to the receiver supply Ground.

### **Serial Communication Protocol**

#### **General**

Incoming data is continually monitored by the RCA15-HR on its serial input line. Each byte of data is formatted as an eight bit word without parity, preceded by one start bit and followed by one stop bit.

Transmission and reception of data up to 19.2K Baud is possible, the actual rate being selected by six position header links on the communications module. The Baud rate depends upon the communications, hardware specification, distance and cable type.

For Baud Link settings see the previous pages of Chapter 7.

4 communication formats, FAST (MANTRABUS), MODBUS, ASCII and PRINTER, are selected from the mnemonic CP via the keypad, of the programmer.

#### **Fast MANTRABUS Format - selected when CP is 128**

To signify commencement of a new 'block' of data, the HEX number FFH is used as a 'frame' character, followed by the station number of the unit under interrogation. This is entered via the RCA15-HR keypad under mnemonic SDSt and ranges from 0-254). The RCA15-HR acts upon incoming data only if its own station number immediately follows the FFH character.

New data must be received as a string of four nibbles (bits 7-4 set to zero) which are assembled into two bytes and written into the variables store within the RCA15-HR. The most significant nibble must be received first and the last nibble must have the most significant bit (bit 7) set to indicate the end of data. This is followed by the checksum. The data transmitted from the RCA15-HR is always sent as complete bytes. The station number precedes the data and the checksum follows the data. The data format used is signed 15 Bit. The most significant Bit of the most significant Byte is set for negative numbers.

#### **Operation**

There are two modes of operation, namely data requests by the host controller and data changes. Data requests from the RCA15-HR consist of either a complete dump of the data variables stores in RAM or the display reading. Data changes consist of writing new data to RCA15-HR variables, thus changing parameters such as Set Points, in flights etc.

An acknowledgement message is returned to the RCA15-HR to indicate that the new data has been acted upon.

## Updating

The required mode or variable to be updated is determined by the station number followed by the command byte. An EXOR checksum consisting of the station number command byte and any following data must be appended to the received data. It is most important that the byte proceeding the checksum must have its most significant bit set to signify the end of data.

The RCA15-HR works out its own checksum and, if it disagrees with the received one, a not acknowledge (NAK) message is returned.

## Communications Commands

The following is a list of commands available for reading to or writing from the RCA15-HR.

Command No.	Description
1	Data dump including Gross & Net values
2	Returns Gross & Net values
3	Spare
4	Write to channel number (sets current transducer)
5	Write to SETP1
6	Write to IN-FT1
7	Write to SETP2
8	Write to IN-FT2
9	Write to HYST
10	Write to LATCH
11	Write to ACTION
12	Write to OP LO
13	Write to OP HI
14	Write to CALL
15	Write to CALH
16	Write to ADCALL
17	Write to ADCALH
18	Write to CAL1 I
19	Write to CAL1 d
20	Write to CAL2 I
21	Write to CAL2 d
22	Write to CAL3 I
23	Write to CAL3 d
24	Write to CAL4 I
25	Write to CAL4 d
26	Write to DP
27	Write to A-TARE
28	Write to SCSTDY
29	Write to DISPAV
30	Write to RESOL
31	Write to TSENS
32	Write to FILTER
33	Write to CP
34	Write to SDSt
100	Request AUTOTARE
101	Request RELAY RESET
102	Reset PEAK HOLD
103	Reset TARE VALUE TO ZERO
104	Set display to GROSS
105	Set display to NET
106	Disable EEROM
107	Enable EEROM & READ TO IT
108	Enable EEROM & WRITE TO IT
109	Disable KEYPAD
110	Enable KEYPAD
111	Set A/D



**COMMAND 1** Request for all data:

DATA TRANSMITTED TO RCA15-HR FOR COMMAND 1  
0FFH, Station Number, 081H, Chksum

Where Chksum = Station number EXOR with 081H. Example: To obtain a complete dump of the variables in the RCA15-HR whose Station number is 47 send the following Data:-

0FFH, 02FH, 081H, 0AEH

    |  
    Note MS Bit Set

**RESPONSE TO COMMAND 1 FROM RCA15-HR**

**Bytes**

1	SDSt
2, 5	Gross Value
6-9	Net Value
10	Status Flag
11-14	tRAN/CHANNEL
15-18	PASS
19-22	SETPT1
23-26	IN-FT1
27-30	SETPT2
31-34	IN-FT2
35-38	HYST
39-42	LATCH
43-46	ACTION
47-50	OP LO
51-54	OP HI
55-58	CALL
59-62	CALH
63-66	ADCALL
67-70	ADCALH
71-74	INPUT A
75-78	DISP A
79-82	INPUT B
83-86	DISP B
87-90	INPUT C
91-94	DISP C
95-98	INPUT D
99-102	DISP D
103-106	Dp
107-110	A-TARE
111-114	SCSTDY
115-118	DISPAV
119-122	RESOL
123-126	TSENS
127-130	FILTER
131-134	CP
135-138	SDSt
139-142	LOG NUMBER
143	EEROM STATUS
144	EX-OR CHEKSUM

**COMMAND 2 REQUEST DISPLAY DATA**

DATA transmitted to RCA15-HR for Command 2.  
0FFH, Station number, 082H, Chksum

Where Chksum = Station number EXOR with 082H

Example: To obtain the display reading of an RCA15-HR whose station number is 47 send the following Data:

0FFH, 02FH, 082H, 0ADH

    |  
    Note MS Bit Set

#### RESPONSE TO COMMAND 2 from RCA15-HR

##### BYTE

1	SDSt
2-5	GROSS
6-9	NET
10	STATUS FLAG
11	DECIMAL POSITION
12	EX-OR CHECKSUM

#### STATUS FLAG

Bit	Flag
0	RELAY 1 ON
1	RELAY 2 ON
2	NOT USED
3	NOT USED
4	NOT USED
5	NOT USED
6	SCALE STEADY
7	GROSS/NET DISPLAY SELECTED

**Commands 4 TO 34:** Write data to RCA15-HR parameter

Commands 4 to 34 all have the same format.

Format for data transmitted to RCA15-HR for Commands 4 to 34:-

0FFH, Station No, Command No, MSN, NIB7, NIB6, NIB5, NIB4, NIB3, NIB2, LSN, CHKSUM

Where MSN = Most significant nibble of data

NIB7-2 = Nibble of data between MSN and LSN

LSN CHKSUM = Least significant nibble of data with MSBIT set

= The following EXOR'd with each other, Station number, command number, MSN, NIB7-2, LSN with MSBIT set

Example: To change Dp to 3 on a RCA15-HR whose station number is 47. The following data is sent.

0FFH,02FH,01AH,00,00,00,00,00,00,00,83H, 0A3H

    |  
    Note MSBIT set

#### Response to COMMAND 4 to 34

If the data has been accepted by the RCA15-HR then the following acknowledgement string is transmitted by the RCA15-HR.

Station number, 06H (ACK)

If there are any errors with the data received by the RCA15-HR then the following

Not Acknowledgement (NAK) string is transmitted by the RCA15-HR:-

Station number, 015H (NAK)

#### Commands 100 to 107

These commands perform action and require only the command number to be transmitted to the RCA15-HR i.e. To disable the keypad of device 47 using command 105 the following data is sent

```
OFFH,2FH,E9H,C6H
  |
  MS BIT SET
```

These commands will be acknowledged by an 'ACK' or if an error a 'NAK' proceeded by the station number.

**Example of a Basic Code to Communicate with Fast MANTRABUS**

open the serial port with no handshaking  
**OPEN"COM2:4800,N,8,1,RS,DS,BIN" FOR RANDOM AS#1**  
 request display from device 1

Frame FF	Station No 1	Command 2 And add 80 hex to this byte as it is the last before as the checksum	Checksum of all bytes except frame
----------	-----------------	--------------------------------------------------------------------------------------------	---------------------------------------

**talk\$=CHR\$(&HFF)+CHR\$(&H1)+CHR\$(&H82)+CHR\$(&H1 XOR&H82)**

*print the string to the port*  
**PRINT#1,talk\$;**  
*(must add semicolon after string to stop transmitting a carriage return)*  
*wait for a while (this depends on how many bytes you are expecting and the baud rate!)*  
*input all the bytes in the serial buffer*  
**input.from.rca-hr\$=INPUT\$(LOC(1),#1)**

**Modbus Section**

This modbus protocol has been implemented in accordance with:-  
 Modicom Modbus Protocol Reference Guide P1 - MBUS - 300 Rev.C

The following conditions apply:-

- Baud Rate must be set to 9600
- The format is RTU
- Data transfer is considered to be Half Duplex, using 2 or 4 wire RS485 medium.
- UART's shall be set for 8 bit word , 1 start bit , 1 stop bit & no parity
- Data transfer is considered to be half duplex using a 2 or 4 wire RS485 medium.

**Modbus Implementation For High Resolution - CP = 130**

**Commands**

The command used for reading of the RCA15-HR shall be command 03, READ OUTPUT REGISTER. The RCA15-HR data, including display & programmable parameters, shall be considered to be 32 bit "Holding registers" accessed as two 16 bit words. Data format will be signed 31 bit with the MS bit of the MS byte being the polarity.

The command for writing data & performing "actions" shall be command 16, PRESET MULTIPLE REGISTERS. All write commands must be 2 register bytes long. Multiple writing to 32 bit registers is therefore not allowed.

A processing time for The RCA15-HR communications software has been estimated at 6mS.

Note:- 'Broadcast' messages Using address 0 is **NOT SUPPORTED**

## Exception Responses

The following exception codes will be used only

- 01 Illegal function
- 02 Illegal data address
- 03 Illegal value

These codes have been indicated as the minimum error handling system required Modcom. A fault log shall not be implemented by the RCA15-HR

## Register Allocation

Register shall be allocated the following values. Odd values are used as a register is only 16 bits & data will be read as 32 bits. For action commands data is ignored but again 2 registers must be written to. See examples below.

Note: The 40000 may be dropped if the host does not support addresses in this range, therefore 40001 becomes 1, 40003 becomes 3, etc.

- 40001 GROSS DISPLAY VALUE
- 40003 NET DISPLAY VALUE
- 40005 STATUS BYTE. INCLUDES SETPOINT STATUS, EEROM (See Page 7-11)
- 40007 DUMMY for continuity only
- 40009 CHAN
- 40011 PASS
- 40013 SETPT1
- 40015 IN-FT1
- 40017 SETPT2
- 40019 IIN-FT2
- 40021 HYST
- 40023 LATCH
- 40025 ACTION
- 40027 OP L
- 40029 OP H
- 40031 ACALL
- 40033 ACALH
- 40035 ADCALL
- 40037 ADCALH
- 40039 DTP1I
- 40041 DTP1D
- 40043 DTP2I
- 40045 DTP2D
- 40047 DTP3I
- 40049 DTP3D
- 40051 DTP4I
- 40053 DTP4D
- 40055 DPSEL
- 40057 DISZER
- 40059 SCALES
- 40061 AVRGE
- 40063 RESOL
- 40065 GAIN
- 40067 FILTER
- 40069 CP
- 40071 SDST
- 40073 LOGNUM LOG NUMBER printer only

## Action Commands

- 40101 DO AUTOTARE

- 40103 DO LATCH RELAY RESET
- 40105 DO PEAK HOLD RESET
- 40107 RESET TARE VALUE TO ZERO
- 40109 SET DISPLAY TO GROSS
- 40111 SET DISPLAY TO NET
- 40113 DISABLE EEROM
- 40115 ENABLE EEROM & READ DATA FROM IT INTO RAM
- 40117 ENABLE EEROM & WRITE DATA IN RAM TO IT
- 40119 DISABLE KEYPAD
- 40121 ENABLE KEYPAD
- 40123 RECONFIGURE A/D AFTER WRITE TO GAIN OR FILTER

**EXAMPLES**

The following are examples of the commands. Channel 1 has been used for examples

**Read NET value from Channel 1**

Data sent from PLC 01 03 9C 43 00 02 1B 8F

Data sent from RCA15-HR 01 03 9C 43 00 02 ,MSB, NMSB, NLSB, LSB, CRC-16 HI, CRC-16 LO

**Auto-tare Channel 1**

Data sent from PLC 01 10 9C A5 00 02 04, xx, xx, xx, xx, CRC-16 HI, CRC-16 LO

Where xx = Don't care

Data sent from RCA15-HR 01 10 9C A5 00 02 CRC-16 HI, CRC-16 LO

**Set Setpoint 1 on Channel 1**

Data sent from PLC 01 10 9C 4D 00 02 D1, D2, D3, D4, CRC-16 HI, CRC-16 LO

Where D1 = data MSB, D2 = data NMSB, D3 = data NLSB, D4 = data LSB

Data sent from RCA15-HR 01 10 9C 4D 00 02 CRC-16 HI, CRC-16 LO

**A note about EEROM**

All user set parameters are stored in EEROM where they are recalled on power up. The EEROM has a limited number of write cycles of between 10,000 & 1,000,000. If setpoint data is to be written to the RCA15-HR we suggest disabling the EEROM from the comms using register 40113. This register is written to with no data as the Auto-tare command.

**Disable EEROM on Channel 1**

Data sent from PLC 01 10 9C B1 00 02 04, xx, xx, xx, xx, CRC-16 HI, CRC-16 LO

Where xx = Don't care

Data sent from RCA15-HR 01 10 9C B1 00 02 CRC-16 HI, CRC-16 LO

**ASCII Protocol**

**Host Transmission**

The command structure is based on the following format

Framing Character	Address	Separator	Command	Response	Data	End of frame
!	001	:	CALH	=	-99.9999	<CR>

For example !001:SETP1=123.456<CR>

An explanation of each field is as follows.

**Framing character:** A single “!” is used to “frame up” the receiving devices allowing all instruments to see the start of a new message. The “!” character will only be transmitted by the host for framing purposes

**Address:** The Address is always 3 ASCII characters representing the devices to which the command is intended. Address 999 is reserved for Broadcast addressing for which there is no response.

**Separator:** Must always be sent by host. As no Checksum or message verification technique is used this separator character is a further check by the instrument on the incoming message.

**Command:** Up to 6 alpha-numeric characters can be used in this field. The mnemonic approach has been used as this would be intended to be as the mnemonics will appear to the user from the 7 segment display thus saving the user for remembering a command list. Upper and lower case can be used within field as no discrimination is made

**Response:** Defines what sort of response is expected. If a “=” appears here then data is expected to follow. If a “?” is received then the host is expecting data back from the instrument. If nothing is received then the command is expected to be an action type i.e. Tare, relay reset. In all cases the instrument will respond with data (see Instrument response) except when the address is 999 which is a general broadcast address.

**Data:** This field can include any printable ASCII characters except “!”. A maximum string length of 40 characters will apply to this field. The field will be decoded by a command specific routine in the instrument. This open approach allows good flexibility in the data into the instrument which could include modem strings Pass words etc. etc.

**End of frame:** A <CR> must **always** transmitted to indicate end of frame & it will be from this point that the data will be decoded from the instruments receive buffer & acted upon

There are 3 basic command types, command read which are used to read data from an instrument, command write which writes data into the instruments & action commands which perform an instrument function such as tare or EEROM disable. The following are examples of the 3 types.

#### Command Read

Framing Character	Address	Separator	Command	Response	Data	End of frame
!	001	:	disp	?		<CR>

#### Command Write

Framing Character	Address	Separator	Command	Response	Data	End of frame
!	001	:	RESOL	=	0.10	<CR>

#### Command Action

Framing Character	Address	Separator	Command	Response	Data	End of frame
!	001	:	RESREL	?		<CR>

#### Response from Instruments

A response from the instrument is always sent, the only exception being when a “broadcast” command is issued. Broadcast commands will only be accepted for Action & write commands. The responses are as follows :-

**Command Read**

Returns the requested value specified by the command. The length of the alpha-numeric data is not fixed (max. length will be 40 characters). Returned data will be terminated with a <CR>. Examples of returned data are as follows.

2.34<CR>

-56.78<CR>

1999.99<CR>

GEORGE<CR>

If the Command is not understood by the instrument then a “?” is transmitted followed by a <CR> is sent by the instrument.

**Command write.**

If the command & value is accepted by the instrument then a <CR> is transmitted, if not accepted a “?” followed by a <CR> is sent.

**Command action.**

If the command is accepted by the instrument then a <CR> is transmitted, if not accepted a “?” followed by a <CR> is sent.

**Response timing.**

From receipt of the host's terminating <CR> to a response from the instrument is expected to be within 50mS.

**Continuous output stream**

By sending an “XON” the instrument will transmit it's display value every display update until an “XOFF” or framing character is received. The display value can be selected under the “Action” mnemonic. This **MUST** only be used in a 1 to 1 system.

## List of Commands

GROSS	Current gross value.	Read only
NET	Current net value.	Read only
STATUS	Current Status flag.	Read only
TRAN	Transducer selected.	Power on default = 0
PASS	Read only	
SETP1	Setpoint 1	
IN-FT1	In-flight 1	
SETP2	Setpoint 2	
IN-FT2	In-flight 2	
HYST	Hysteresis for setpoint 1 & 2	
LATCH	Latch for setpoint 1 & 2	
ACTION	Output action	
OP LOW	Output Low for An-op scaling	
OP HIGH	Output high for An-op scaling	
CALL	Calibration low point	
CALH	Calibration high point	
ADCALL	A/D value for low calibration point	
ADCALH	A/D value for high calibration point	
INPUTA	4 point linearisation input value A	
DISP A	4 point linearisation display value A	
INPUTB	4 point linearisation input value B	
DISP B	4 point linearisation display value B	
INPUTC	4 point linearisation input value C	
DISP C	4 point linearisation display value C	
INPUTD	4 point linearisation input value D	
DISP D	4 point linearisation display value D	
DP	decimal point position	
A-TARE	Auto-Tare value	
SCSTDY	Scale steady value which must be held for 2 seconds Unit will not Auto tare til scale steady. Can be disabled with value of 0	
DISPAV	Display averaging	
RESOL	Display resolution	
T-SENS	A/D gain	
FILTER	A/D filtering	
CP	Comms protocol.	Read only
SDSt	Serial device station number or Label for printer. Read only	
LOGNUM	Incremental log number for printer. Reset to 0 on power up	

## Action Commands

DOTARE	Perform Auto Tare
RESREL	Reset Latch Relays
RESPH	Reset Peak Hold
RESTAR	Reset Tare value to zero
SETGRS	Set display to Gross value
SETNET	Set display to Net value
DISE2R	Disable E2rom
ENE2RR	Enable E2rom & read from it
ENE2RW	Enable E2rom & write RAM to it
DISKEY	Disable Keys
ENKEY	Enable Keys
SETAD	Reset A/D using filter & t-sens values
HELLO	Used to determine if device present. Returns CR

## **RCA15-HR Printer Format**

(CP must be set between 0 - 127)

Printer selection enables the RCA15-HR to print its current display value to a printer via its communications port. This display value can either be assigned a date and time stamp and/or a log number depending on the user set



options entered under mnemonic 'CP'. The log number can be reset or preset using the mnemonic 'Ln'. This value is not saved on power fail. A label can be suffixed to the printed display value using the mnemonic 'Lab'. A large range of labels are available to the user.

The time and date are set in the TDP printer itself using its own menu. The printer allows the entry of an additional custom text message.

Three connections are required between the RCA15-HR communications port and the printer with a maximum cable length of 100 meters.

All standard RCA15-HR options are available with the exception of the communications modules, which cannot be connected when the printer option is used.

#### **Additional Mnemonics for the Printer Operation:**

When the printer option is fitted further mnemonics are included in the normal range. After the dP r mnemonic are the following:-

CP At this mnemonic the printer type and print format number is selected. This number being appropriate to the type of printer used. Details are advised with each type of printer selected.  
Present types available are:- For the ITT IPP-144-40E printer the following numbers apply

0 Prints a sequential log number with the current display and unit of measure  
e.g. **00014 0011.3 tonne**

1 Prints date and time with a sequential log number, current display and unit of measure  
e.g. **00015 0001.7 tonne**

2 **13.07.99 12:05:06**  
Prints a sequential log number, current display, unit of measure with customer text message No 1  
e.g. **MANTRACOURT ELECTRONICS RCA15-HR PRINTER**  
**00012 00023. tonne**

3 Prints date and time with a sequential log number, current display, unit of measure and a customer text message No.1  
e.g. **MANTRACOURT ELECTRONICS RCA15-HR PRINTER**  
**00013 0023. tonne**  
**13.07.99 12:03:04**

4-7 Digitec 6700 series

8,9 Amplicon AP24 and AP40

10 Eltron LP2142 - (The label file must be called 'MEL' and the label must contain a LOG NUMBER, THE DISPLAY VARIABLE & a LABEL (not zero).  
LOG NUMBER, THE DISPLAY VARIABLE & a LABEL (not zero)

12 ASCII string on print command

125 Continuous ASCII stream of the display data, without Log Number transmitted on every display update

126 Continuous ASCII stream of the display data, with Log Number transmitted on every display update

*Note:1 9 gives an inverted print out*

*Note: 2 it is anticipated that further types of printer will be added, and additional numbers will be allocated as appropriate*

## **Chapter 8 Trouble Shooting Guide**

This chapter is designed to assist in the identification of problems relating to the installation and setting up of the RCA15-HR.

### **1. General Connection and setup parameters.**

#### **No display on power up.**

- a) Check supply is present at the RCA15-HR terminals.

#### **Display shows (-1 or 1) continually, without a weight applied to the Strain Gauge.**

- a) Check input connections to the RCA15-HR from the Strain Gauge.
- b) If connecting a 4 wire device ensure terminals 1&2 and 5&6 are linked.
- c) Check Strain Gauge output between input terminals 3&4 of the RCA15-HR.
- d) Check that the CALH weight is applied and is not the same or lower than CALL

#### **Display over ranges (-1 or 1) when, or before, the maximum required weight is applied to the Strain Gauge.**

- a) Check output of Strain Gauge is set to the correct sensitivity settings on the DIL switch

#### **Display very noisy**

- a) If using a 4 wire device ensure terminals 1&2 & 5&6 are linked.
- b) Check output voltage of Strain Gauge.

#### **Display operating in wrong direction**

- a) Check connections to input terminals 3&4 are correct way round.
- b) Check the type of Strain Gauge - compression or tension.

#### **Unit will not auto calibrate**

- a) Check that CALH is not zero and its weight is greater than CALL.
- b) Check that input is not overranged on CALH weight.

#### **Access to parameters not possible beyond the PASSWORD (PASS)**

- a) Check for special password (contact supplier) with your company.

### **2. Relay Output Module**

#### **Incorrect Relay Operation**

- a) Check set point, in flight and hysteresis values are correct.
- b) Check latching and inversion settings in output action (ACTION) are correct.
- c) Check connections to output terminals.

#### **Remote function (Auto Tare, Peak Hold / Latched , printer fails to operate)**

- a) Check 'DP-r' for correct value to ensure desired function selected.

## Chapter 9 RCA15-HR Specifications

### Strain Gauge Input

**Calibration** Automatic digital by use of keypad and 1 (or 2) known weights giving  $\pm 0.0015\%$  linearity.

**Initial Calibration** Linear mV/V input, using auto cal giving  $\pm 0.0015\%$  linearity.

**SI Units/Linearisation** 4 point linearisation and conversion of mV/V value into engineering units. Optional facility to download mV/V value to a Computer for conversion using a third order polynomial equation.

**Auto Tare** Auto Tare values can also be viewed and manually changed if required. Auto tare value is retained on power down. Auto Tare is affected from the field terminals.

**Input Sensitivity Range** 1.25 to 30mV/V (selectable ranges  $\pm 1.25, 2.5, 5, 7.5, 15, 30\text{mV/V}$ )

**Zero Temperature Coefficient**  $< 0.0005\%$  FSO/ $^{\circ}\text{C}$  typical with 2.5 mV/V sensitivity selected

**Span Temperature Coefficient**  $< 0.0017\%$  reading / $^{\circ}\text{C}$  ( $< 0.007\%$  reading / $^{\circ}\text{C}$ )

**Excitation** 9.6V DC nominal, 160mA maximum

**Compensation** By  $\pm$  sense wires to compensate for cable, connection volt drops and any variation in 10V supply.

**Display Resolution** 1 part in 524,287

**Linearity** Less than 1 part in 65,000 ( $< \pm 0.0015\%$  FSO)

**Drift** 0.002% /C typical @ 2.5mV/V

**Repeatability**  $< \pm 0.002\%$  reading over 90 days

**Display Update Rate** Programmer keypad selectable between 0.1 and 25.5 seconds

**Display Average** Set by programmer keypad, up to 64 standard updates

### DC Analogue Outputs

Range	Max Drive	Typical	Accuracy	
MIN	MAX	% of reading	% of FSD	
+4	+20mA	20V (1K)	$\pm 0.08\%$	$\pm 0.08\%$
0	+10V	2mA	$\pm 0.08\%$	$\pm 0.08\%$

### Control / Alarm Relay Output

2 SPCO relays, SETPT1 and SETPT2

Contact Rating 50V @ 500mA DC

Set Point, In Flight Compensation, Hysteresis, Latching and Relay Inversion are set digitally using programmer keypad and display, in engineering units.

Hysteresis value applies to both SETPT1 and SETPT2. (Fail safe operation by setting inversion to give normally energized operation).

Latching Reset By volt free contact to field terminals or by communication.

## ***The Communications Port Data***

### **Operation**

All RCA15-HR display data can be retrieved via communications port along with relay and EEPROM status.

All RCA15-HR user configurable data can be changed including EEPROM enable/display and relay reset. (RCA15-HR Station Number cannot be changed).

The RCA15-HR communications port provides for a 2 way data link. An intelligent host e.g. Personal Computer, Main Frame or PLC is able to acquire the RCA15-HR's displayed value and read or modify the user configurable parameters, using any of the following:-

- a) RS232 - for a one to one communication (as in the case of a printer, PC or PLC).
- b) RS485 - for the connection of up to 25, RCA15-HR units on a single RS485 line.
- c) 20mA Current Loop - for up to 250, RCA15-HR units on a single RS232 line, via the IF25 interface. With high noise immunity and isolation over distances up to 1Km.
- d) Baud Rates - 300, 600, 1200, 4800,9600, (19,200 Fast MANTRABUS Format ONLY)
- e) Isolation -  $\pm 130V$  RMS or DC max to analogue input or any other port.

Protocols available are ASCII and Fast MANTRABUS Format selectable by the CP mnemonic on the display of the RCA15-HR programmer.

### ***Data Retention and Protection***

Retention: 10 years for set values, minimum of 10,000 write cycles, but typically 1,000,000.

Protection of data and function(s): Watchdog timer giving repeat auto resets. Impending power fail detection and shutdown. Low power detection and hold off.

### ***Environmental***

Storage temperature -20 to +70 °C

Operating temperature -10 to +50 °C

Relative humidity 95% max non condensing

Case sealing  
To IP65

### ***CE Approvals***

European EMC Directive 2004/108/EC  
BS EN 61326-1:2006  
BS EN 61326-2-3:2006

Low Voltage Directive 2006/95/EC  
BS EN 61010-1:2001  
Rated for Basic Insulation  
Normal Condition  
Pollution Degree 2  
Permanently Connected  
Insulation Category III

## Physical

Rack dimensions	482 x 130 x 185mm
Weight	5.2kg
Terminals	2.5mm, saddle field terminals
Accessibility	All electronics accessible through front panel.

## Power Supplies

97 - 120/210 - 260 VAC 50 - 60Hz, 50W

## RCA15-HR Order Codes

<b>Input</b>	Standard Strain Gauge		10V DC / 160mA	RUA1-EX /UAHRLC (Remote programming)
<b>Outputs</b>	Standard Analogue	Output DC voltage DC current	Range 0V to 10V 4 to 20mA	RUA2-EX /UAHRLC (Local Display/programming)
<b>Optional Modules</b>				
<b>Communications Port</b>		Current Loop RS232/485		(RC1) (RC3)
<b>Output</b>	Control/Alarm Relay Remote Relay Driver Module	Output 2 Relays	Function SPCO on SETPT1& 2	(RR1) (I <sup>2</sup> C)
<b>Power Supplies</b>		110 - 120/220 - 240V AC 50 - 60Hz 50W One supply		(RS1)
<b>Program Unit</b>		Remote Hand Held		(LP3)
<b>Rack Mounting</b>		12 x RL1 (Remote Display)		RF1
		8 x RL2 (Local Display)		RF2
		Blanking panels for RF1		RB1
		Blanking panels for RF2		RB2

Example:

6 x RUA2-EX/UAHRLC  
6 x RC3  
6 x RR1  
1 x RF2  
1 x RS1  
2 x RB2

This lists 6 High Resolution Strain Gauge input channels with local displays, RS232/485 communications, 2 Relay Outputs fitted into a rack, having a power supply and 2 blanking panels.

Rack for 6 Local Display modules with Digital Output Modules.

#### RCA15-HR Accessories

The following accessories are available to allow for expansion of systems:

	Function	Order Code
IF25 Interface	Connect up to 25 RCA15-HRs NOTE: Details of the unit appears in a separate publication.	IF25
Printers	Time / date and display data Display data only	TDP DP

#### *Instrument Setup Record Sheet*

Product	
Product Code	
Serial No	
Tag No	
Date	
Location	
Measurement type, range & engineering units	
Communication / Baud Rate	
RCA15-HR	VALUE
PASS	
SETPT1	
IF1	
SETPT2	
IF2	
HYS	
OA	
CALL	
CALH	
At	
dA	
OP LO	
OP HI	
dP	
CP	
SdSt or LAB	
Ln (for printer)	
rS	

## WARRANTY

All RCA-HR products from Mantracourt Electronics Ltd., ('Mantracourt') are warranted against defective material and workmanship for a period of (3) three years from the date of dispatch.

If the 'Mantracourt' product you purchase appears to have a defect in material or workmanship or fails during normal use within the period, please contact your Distributor, who will assist you in resolving the problem. If it is necessary to return the product to 'Mantracourt' please include a note stating name, company, address, phone number and a detailed description of the problem. Also, please indicate if it is a warranty repair.

The sender is responsible for shipping charges, freight insurance and proper packaging to prevent breakage in transit.

'Mantracourt' warranty does not apply to defects resulting from action of the buyer such as mishandling, improper interfacing, operation outside of design limits, improper repair or unauthorised modification.

No other warranties are expressed or implied. 'Mantracourt' specifically disclaims any implied warranties of merchantability or fitness for a specific purpose. The remedies outlined above are the buyer's only remedies. 'Mantracourt' will not be liable for direct, indirect, special, incidental or consequential damages whether based on the contract, tort or other legal theory.

Any corrective maintenance required after the warranty period should be performed by 'Mantracourt' approved personnel only.



Ⓒ In the interests of continued product development, Mantracourt Electronics Limited reserves the right to alter product specifications without prior notice.

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